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Translation of the original operating instructions

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1. SAFETY REGULATIONS AND NOTES

Please read these operating instructions carefully before starting to work with the device. Observe the following warnings to prevent malfunctions or physical damage to both property and people.

These operating instructions are to be regarded as part of this device. If the device is sold or transferred, the operating instructions must accompany it.

These operating instructions may be duplicated and forwarded for information about potential dangers and their prevention.

1.1 Levels of hazard warnings

These operating instructions use the following hazard levels to indicate potentially hazardous situations and important safety regulations:



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DANGER

Indicates an imminently hazardous situation which, if not avoided, will result in death or serious injury. Compliance with the measures is mandatory.

WARNING

Indicates a potentially hazardous situation which, if not avoided, could result in death or serious injury. Exercise extreme caution while working.

CAUTION

Indicates a potentially hazardous situation which, if not avoided, may result in minor or moderate injury or damage of property.

NOTE

A potentially harmful situation can occur and, if not avoided, can lead to property damage.

1.2 Staff qualification

The device may only be transported, unpacked, installed, operated, maintained and otherwise used by qualified, trained and authorised technical staff.

Only authorised specialists are permitted to install the device, to carry out a test run and to perform work on the electrical installation.

1.3 Basic safety rules

Any safety hazards stemming from the device must be re-evaluated once it is installed in the end device.

Observe the following when working on the unit:

⇒ Do not make any modifications, additions or conversions to the device without the approval of ebm-papst.

1.4 Electrical voltage

- ⇒ Check the electrical equipment of the device at regular intervals, refer to chapter 6.3 Safety test.
- ⇒ Replace loose connections and defective cables immediately.



DANGER

Electrical load on the device

- Risk of electric shock
- → Stand on a rubber mat if you are working on an electrically charged device.

WARNING

Terminals and connections have voltage even with a unit that is shut off

Electric shock

 \rightarrow Wait five minutes after disconnecting the voltage at all poles before opening the device.





CAUTION

In the event of failure, there is electric voltage at the rotor and impeller

The rotor and impeller are base insulated.

 \rightarrow Do not touch the rotor and impeller once they are installed.

CAUTION

If control voltage is applied or a speed setpoint is stored, the motor will restart automatically, e.g. after a mains failure.

Risk of injury

- → Keep out of the device hazard zone.# When working on the device, switch off the mains power and ensure that it cannot be switched back on.
- \rightarrow Wait until the device stops.
- → After working on the device, remove any tools used or other objects from the device.

1.5 Safety and protective functions



DANGER Protective device missing and protective device not functioning

Without a protective device there is a risk of serious injury, for instance when reaching into the device during operation.

- → Operate the device only with a fixed protective device and guard grille.# The fixed protective device must be able to withstand the kinetic energy of a fan blade that becomes detached at maximum speed. There must not be any gaps which it is possible to reach into with the fingers, for example.
- → The device is a built-in component. As the operator, you are responsible for ensuring that the device is secured adequately.
- → Stop the device immediately if a protective device is found to be missing or ineffective.

1.6 Electromagnetic radiation

Interference from electromagnetic radiation is possible, e.g. in conjunction with open and closed-loop control devices.

If unacceptable emission intensities occur when the fan is installed, appropriate shielding measures have to be taken by the user.

NOTE

Electrical or electromagnetic interferences after integrating the device in installations on the customer's side.

→ Verify that the entire setup is EMC compliant.

1.7 Mechanical movement



DANGER Rotating device

Body parts that come into contact with the rotor and impeller can be injured.

- \rightarrow Secure the device against accidental contact.
- → Before working on the system/machine, wait until all parts have come to a standstill.

WARNING

Rotating device

Long hair, dangling items of clothing, jewellery and similar items can become entangled and be pulled into the device. Risk of injury.

→ Do not wear any loose-fitting or dangling clothing or jewellery while working on rotating parts.# Protect long hair with a cap.

1.8 Emission

WARNING

Depending on the installation and operating conditions, a sound pressure level greater than 70 dB(A) may arise. Danger of noise-induced hearing loss

- \rightarrow Take appropriate technical safety measures.
- → Protect operating personnel with appropriate safety equipment, e.g. hearing protection.
- \rightarrow Also observe the requirements of local agencies.

1.9 Hot surface



CAUTION High temperature at the electronics housing Risk of burns

 \rightarrow Ensure sufficient contact protection.

1.10 Transport

NOTE

- Transport of device
- \rightarrow Transport the device in its original packaging only.
- \rightarrow Secure the device so that it does not slip, e.g. by using a clamping strap.

WARNING

Transportation of fan

Injuries from tipping or slipping

→ Always transport the fan carefully and only in its original packaging. Impact arising from setting down too hard or at an angle can cause bearing damage or deformation at the frame and impeller. #The fans must always be transported and handled such that they cannot tip over. #Transport the fan "upright", in other words with the axis horizontal. #Secure the fan(s) with a lashing strip for example so that nothing can slip or tip up, particularly when stacking several fans. #Also make allowance for possible wind forces.

1.11 Storage

- ⇒ Store the device, partially or fully assembled, in the original packaging in a clean, dry and weatherproof place free of vibrations.
- ⇒ Protect the device against environmental effects and dirt until final installation.
- ⇒ We recommend storing the device for no longer than one year in order to guarantee trouble-free operation and longest possible service life.
- ⇒ Even devices explicitly intended for outdoor use are to be stored as described prior to commissioning.
- ⇒ Maintain the storage temperature, see chapter 3.6 Transport and storage conditions.
- ⇒ Please make sure that all screwed cable glands are fitted with dummy plugs.



Translation of the original operating instructions

2. PROPER USE

The device is exclusively designed as a built-in device for conveying air according to its technical data.

Any other usage above and beyond this does not conform with the intended purpose and constitutes misuse of the device.

Customer equipment must be capable of withstanding the mechanical and thermal stresses that can arise from this product. This applies for the entire service life of the equipment in which this product is installed.

Proper use also includes:

- Use the device in power systems with earthed neutral (TN/TT power systems) only.
- Conveying of air at an ambient air pressure of 800 mbar to 1050 mbar.
- Using the device in accordance with the permitted ambient temperature, see chapter 3.6 Transport and storage conditions and chapter 3.2 Nominal data.
- Operating the device with all protective features in place.
- Minding the operating instructions.

Improper use

Using the device in the following ways is particularly prohibited and may cause hazards:

- Operating the device with an imbalance, e.g. caused by dirt deposits or icing.
- Resonance mode, operation with heavy vibrations. These also include vibrations that are transmitted from the customer system to the fan.
- Opening the terminal box during operation.
- Moving air that contains abrasive particles.
- Moving highly corrosive air, e.g. salt spray mist. Exceptions are devices that are intended for salt spray mist and protected accordingly.
- Moving air that contains dust pollution, e.g. suctioning off saw dust.
- Operating the device close to flammable materials or components.
- Operating the device in an explosive atmosphere.
- Using the device as a safety component or for taking on safetyrelated functions.
- Operation with completely or partially disassembled or modified protective features.
- In addition, all application options that are not listed under proper use.



3. TECHNICAL DATA

3.1 Product drawing



All measures have the unit mm.

1	Cable diameter min. 8 mm, max. 12 mm, tightening torque 2.5±0.4 Nm
2	Cable diameter min. 6 mm, max. 10 mm, tightening torque 2.5±0,4 Nm
	Cable diameter min. 4 mm, max. 7 mm, tightening torque 2.5±0.4 Nm (use must be made of sealing ring provided)
3	Tightening torque 1.5±0.2 Nm
4	Inlet nozzle with pressure tap (k-factor: 116)
5	Mounting holes for FlowGrid



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3.2 Nominal data

Motor	M3G084-GF
	1
Phase	3~
Nominal voltage / VAC	400
Nominal voltage	380 480
range / VAC	
Frequency / Hz	50/60
Type of data definition	ml
Speed (rpm) / min ⁻¹	3010
Power input / W	1230
Current draw / A	1.9
Min. ambient	-25
temperature / °C	
Max. ambient	40
temperature / °C	

ml = Max. load · me = Max. efficiency · fa = Running at free air

cs = Customer specs \cdot cu = Customer unit

Subject to alterations

3.3 Data in accordance with ecodesign regulation EU 327/

2011

	Actual	Request 2015	
01 Overall efficiency ηes / %	66.7	52.3	
02 Measurement category	A		
03 Efficiency category	Static		
04 Efficiency grade N	76.4	62	
05 Variable speed drive	Yes		
06 Year of manufacture	The year of manufacture is specified on the rating plate on the product.		
07 Manufacturer	ebm-papst Mulfingen GmbH & Co. KG County court Stuttgart · HRA 590344 D-74673 Mulfingen		
08 Туре	K3G310-PT08-J4		
09 Power input Ped / kW	1.18		
09 Air flow qv / m³/h	3635		
09 Pressure increase total psf / Pa	729		
10 Speed (rpm) n / min ⁻¹	3010		
11 Specific ratio*	1.01		
12 Recycling/disposal	Information on recyclin provided in the operatir	g and disposal is ng instructions.	
13 Maintenance	Information on installat maintenance is provide instructions.	ion, operation and ed in the operating	
14 Additional components	Components used to c efficiency that are not a measurement category CE declaration.	alculate the energy apparent from the vare detailed in the	

* Specific ratio = 1 + pfs / 100 000 Pa

Data definition with optimum efficiency. The ErP data is determined using a motor-impeller combination in a standardised measurement configuration.

3.4 Technical features

Mass	15.5 kg
Size	310 mm
Surface of rotor	Coated in black
Material of terminal box	PP plastic
Material of electronics	Die-cast aluminium
housing	
Material of impeller	Aluminium sheet
Material of mounting	Sheet steel, galvanised
nlate	
Material of support	Steel coated in black
bracket	
Material of inlet nozzle	Sheet steel, galvanised
Number of blades	5
Direction of rotation	Cleakwise, seen on reter
Direction of rotation	
Type of protection	IP 55
Insulation class	"F"
Humidity (F)/	H1
environmental	
protection class (H)	
Note ambient	Occasional start-up between -40°C and -
temperature	25°C is permissible.
	For continuous operation at ambient
	temperatures below -25°C (e.g.
	refrigeration applications) we recommend
	our fan version with special low-
	temperature bearings.
Mounting position	Shaft horizontal or rotor on bottom; rotor
	on top on request
Condensate discharge	Rotor-side
holes	
Operation mode	S1
Materials and a second second	Dellheering
Motor bearing	Ball bearing
Technical features	- Output 10 VDC, max. 10 mA
Technical features	- Output 10 VDC, max. 10 mA - Operation and alarm display
Motor bearing Technical features	- Output 10 VDC, max. 10 mA - Operation and alarm display - External 24 V input (programming)
Technical features	- Output 10 VDC, max. 10 mA - Operation and alarm display - External 24 V input (programming) - Alarm relay
Motor bearing Technical features	 - Output 10 VDC, max. 10 mA - Operation and alarm display - External 24 V input (programming) - Alarm relay - Integrated PID controller
Technical features	Output 10 VDC, max. 10 mA Operation and alarm display External 24 V input (programming) Alarm relay Integrated PID controller Motor current limit
Technical features	 - Output 10 VDC, max. 10 mA - Operation and alarm display - External 24 V input (programming) - Alarm relay - Integrated PID controller - Motor current limit - PFC, passive
Motor bearing Technical features	 Output 10 VDC, max. 10 mA Operation and alarm display External 24 V input (programming) Alarm relay Integrated PID controller Motor current limit PFC, passive RS485 MODBUS RTU
Motor bearing Technical features	 Output 10 VDC, max. 10 mA Operation and alarm display External 24 V input (programming) Alarm relay Integrated PID controller Motor current limit PFC, passive RS485 MODBUS RTU Soft start
Motor bearing Technical features	Output 10 VDC, max. 10 mA Operation and alarm display External 24 V input (programming) Alarm relay Integrated PID controller Motor current limit PFC, passive RS485 MODBUS RTU Soft start -Maximum EEPROM write cycles
Motor bearing Technical features	- Output 10 VDC, max. 10 mA - Operation and alarm display - External 24 V input (programming) - Alarm relay - Integrated PID controller - Motor current limit - PFC, passive - RS485 MODBUS RTU - Soft start -Maximum EEPROM write cycles 100,000
Motor bearing Technical features	Output 10 VDC, max. 10 mA Operation and alarm display External 24 V input (programming) Alarm relay Integrated PID controller Motor current limit PFC, passive RS485 MODBUS RTU Soft start -Maximum EEPROM write cycles 100,000 Control input 0-10 VDC / PWM
Motor bearing Technical features	 - Output 10 VDC, max. 10 mA - Operation and alarm display - External 24 V input (programming) - Alarm relay - Integrated PID controller - Motor current limit - PFC, passive - RS485 MODBUS RTU - Soft start -Maximum EEPROM write cycles 100,000 - Control input 0-10 VDC / PWM - Control interface with SELV potential
Technical features	 - Output 10 VDC, max. 10 mA - Operation and alarm display - External 24 V input (programming) - Alarm relay - Integrated PID controller - Motor current limit - PFC, passive - RS485 MODBUS RTU - Soft start -Maximum EEPROM write cycles 100,000 - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains
Technical features	 - Output 10 VDC, max. 10 mA - Operation and alarm display - External 24 V input (programming) - Alarm relay - Integrated PID controller - Motor current limit - PFC, passive - RS485 MODBUS RTU - Soft start - Maximum EEPROM write cycles 100,000 - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Over-temperature protected
Technical features	 - Output 10 VDC, max. 10 mA - Operation and alarm display - External 24 V input (programming) - Alarm relay - Integrated PID controller - Motor current limit - PFC, passive - RS485 MODBUS RTU - Soft start - Maximum EEPROM write cycles 100,000 - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Over-temperature protected - electronics / motor
Technical features	 - Output 10 VDC, max. 10 mA - Operation and alarm display - External 24 V input (programming) - Alarm relay - Integrated PID controller - Motor current limit - PFC, passive - RS485 MODBUS RTU - Soft start - Maximum EEPROM write cycles 100,000 - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Over-temperature protected electronics / motor - Line undervoltage / phase failure distance
Technical features	 Bail bearing Output 10 VDC, max. 10 mA Operation and alarm display External 24 V input (programming) Alarm relay Integrated PID controller Motor current limit PFC, passive RS485 MODBUS RTU Soft start Maximum EEPROM write cycles 100,000 Control input 0-10 VDC / PWM Control interface with SELV potential safely disconnected from the mains Over-temperature protected electronics / motor Line undervoltage / phase failure detection
Technical features	 - Output 10 VDC, max. 10 mA - Operation and alarm display - External 24 V input (programming) - Alarm relay - Integrated PID controller - Motor current limit - PFC, passive - RS485 MODBUS RTU - Soft start - Maximum EEPROM write cycles 100,000 - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Over-temperature protected electronics / motor - Line undervoltage / phase failure detection <= 3.5 mA
Technical features Touch current acc. IEC 60990 (measuring	 - Output 10 VDC, max. 10 mA - Operation and alarm display - External 24 V input (programming) - Alarm relay - Integrated PID controller - Motor current limit - PFC, passive - RS485 MODBUS RTU - Soft start - Maximum EEPROM write cycles 100,000 - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Over-temperature protected electronics / motor - Line undervoltage / phase failure <a href="mailto: detection
Technical features Technical features	 - Output 10 VDC, max. 10 mA - Operation and alarm display - External 24 V input (programming) - Alarm relay - Integrated PID controller - Motor current limit - PFC, passive - RS485 MODBUS RTU - Soft start - Maximum EEPROM write cycles 100,000 - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Over-temperature protected electronics / motor - Line undervoltage / phase failure <= 3.5 mA
Technical features Technical features	 Output 10 VDC, max. 10 mA Operation and alarm display External 24 V input (programming) Alarm relay Integrated PID controller Motor current limit PFC, passive RS485 MODBUS RTU Soft start Maximum EEPROM write cycles 100,000 Control input 0-10 VDC / PWM Control interface with SELV potential safely disconnected from the mains Over-temperature protected electronics / motor Line undervoltage / phase failure detection
Technical features Technical features Touch current acc. IEC 60990 (measuring network Fig. 4, TN system) Electrical leads	 Output 10 VDC, max. 10 mA Operation and alarm display External 24 V input (programming) Alarm relay Integrated PID controller Motor current limit PFC, passive RS485 MODBUS RTU Soft start Maximum EEPROM write cycles 100,000 Control input 0-10 VDC / PWM Control interface with SELV potential safely disconnected from the mains Over-temperature protected electronics / motor Line undervoltage / phase failure detection <= 3.5 mA
Technical features Touch current acc. IEC 60990 (measuring network Fig. 4, TN system) Electrical leads Motor protection	 Bain bearing Output 10 VDC, max. 10 mA Operation and alarm display External 24 V input (programming) Alarm relay Integrated PID controller Motor current limit PFC, passive RS485 MODBUS RTU Soft start Maximum EEPROM write cycles 100,000 Control input 0-10 VDC / PWM Control interface with SELV potential safely disconnected from the mains Over-temperature protected electronics / motor Line undervoltage / phase failure detection <= 3.5 mA Via terminal box Thermal overload protector (TOP) wired
Technical features Technical features Touch current acc. IEC 60990 (measuring network Fig. 4, TN system) Electrical leads Motor protection	 Bail bearing Output 10 VDC, max. 10 mA Operation and alarm display External 24 V input (programming) Alarm relay Integrated PID controller Motor current limit PFC, passive RS485 MODBUS RTU Soft start Maximum EEPROM write cycles 100,000 Control input 0-10 VDC / PWM Control interface with SELV potential safely disconnected from the mains Over-temperature protected electronics / motor Line undervoltage / phase failure detection <= 3.5 mA Via terminal box Thermal overload protector (TOP) wired internally
Technical features Technical features Touch current acc. IEC 60990 (measuring network Fig. 4, TN system) Electrical leads Motor protection Protection class	 Bail bearing Output 10 VDC, max. 10 mA Operation and alarm display External 24 V input (programming) Alarm relay Integrated PID controller Motor current limit PFC, passive RS485 MODBUS RTU Soft start Maximum EEPROM write cycles 100,000 Control input 0-10 VDC / PWM Control interface with SELV potential safely disconnected from the mains Over-temperature protected electronics / motor Line undervoltage / phase failure detection <= 3.5 mA Via terminal box Thermal overload protector (TOP) wired internally I (if protective earth is connected by



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Product conforming	EN 61800-5-1; CE
to standard	
Approval	C22.2 Nr.77 + CAN/CSA-E60730-1;
	EAC; UL 1004-7 + 60730
Remark	Standard conformity as per EN 60335-1
	in preparation



For cyclic speed loads, note that the rotating parts of the device are designed for maximum one million load cycles. If you have specific questions, contact ebm-papst for support.

The surfaces of the products conform to the generally applicable industrial standard. The surface quality may vary during the production period. Strength, dimensional stability and dimensional accuracy are not affected by this.

The colour pigments of the paints used react perceptibly to UV light over the course of time. This does not however have any influence on the technical properties of the products. To prevent the formation of patches and fading, the product is to be protected against UV radiation. Changes in colour are not a reason for complaint and are not covered by the warranty.

3.5 Mounting data

⇒ Secure the mounting screws against accidentally coming loose (e.g. by using self-locking screws).

Strength class for	8.8
mounting screws	

You can obtain additional mounting data from the product drawing if necessary.

3.6 Transport and storage conditions

⇒ Use the device in accordance with its protection type.

Max. permissible	+80 °C
ambient motor temp.	
(transp./ storage)	
Min. permissible	-40 °C
ambient motor temp.	
(transp./storage)	

3.7 Electromagnetic compatibility

EMC interference immunity	Acc. to EN 61000-6-2 (industrial environment)
EMC interference emission	Acc. to EN 61000-6-3 (household environment), except EN 61000-3-2 for professionally used devices with a total rated power greater than 1 kW

If several devices are switched in parallel on the mains side so that the line current of the arrangement is in the range of 16 - 75 A, then this arrangement conforms to IEC 61000-3-12 provided that the short-circuit power Ssc at the connection point of the customer system to the public power system is greater than or equal to 120 times the rated output of the arrangement. It is the responsibility of the installation engineer or operator/ owner of the device to ensure, if necessary after consultation with the network operator, that this device is only connected to a connection point with a Ssc value that is greater than or equal to 120 times the rated output of the arrangement.

4. CONNECTION AND START-UP

4.1 Connecting the mechanical system



Cutting and crushing hazard when removing device from packaging

→ Carefully remove the device from its packaging, only touching the housing. Strictly avoid shocks.# Wear safety shoes and cut-resistant safety gloves.

CAUTION

CAUTION

Heavy load when taking out the device Bodily harm, e.g. back injuries, are possible.

→ Two people should remove the device out of its packaging together.

NOTE

Damage to device from vibration

Bearing damage, reduced service life

- → Forces or impermissibly high vibration levels must not be transmitted to the fan from system components. #If the fan is connected to air ducts, it should isolated from vibrations, for example using compensators or similar elements. #Fasten the fan to the substructure without distorting it.
- ⇒ The fan may not be handled in the area around the inlet nozzle during transport and installation.

There is a risk of damage to the impeller.

- Check the device for transport damage. Damaged devices must no longer be installed.
- Install the undamaged device according to your application.



CAUTION Possibility of damage to the device

Serious damage may result if the device slips during assembly.

→ Keep the device fixed in position at the installation location until all attachment screws have been tightened.

4.2 Connecting the electrical system



DANGER Electric voltage on the device

Electric shock

- \rightarrow Always install a protective earth first.
- \rightarrow Check the protective earth.



Incorrect insulation

Risk of fatal injury from electric shock

- → Use only cables that meet the specified installation requirements for voltage, current, insulation material, load etc.
- → Route cables such that they cannot be touched by any rotating parts.



Electrical load (>50 μ C) between mains wire and protective earth connection after switching of the supply when switching multiple devices in parallel.

- Electric shock, risk of injury
- → Make sure that sufficient protection against accidental contact is provided.

Before working on the electrical connection, the connections to the mains supply and PE must be shorted.



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CAUTION

Electrical voltage

The fan is a built-in component and features no electrically isolating switch.

- → Only connect the fan to circuits that can be switched off with an all-pole separating switch.
- → When working on the fan, you must switch off the installation/machine in which the fan is installed and secure it from being switched on again.

NOTE

Interferences and failures are possible

Maintain a distance to the power supply line when routing the control lines of the device.

→ Ensure a sufficiently large clearance. Recommendation: clearance > 10 cm (separate cable routing)

NOTE

Water penetration into leads or wires

Water enters at the cable end on the customers side and can damage the device.

→ Make sure that the cable end is connected in a dry environment.



Connect the device only to circuits that can be switched off using an all-pole disconnecting switch.

4.2.1 Prerequisites

- ⇒ Check that the data on the type plate match the connection data.
- ⇒ Before connecting the device, ensure that the supply voltage matches the operating voltage of the device.
- ⇒ Only use cables designed for current according to the type plate. For determining the cross-section, follow the basic principles in accordance with EN 61800-5-1. The protective earth must have a cross-section equal to or greater than the outer conductor crosssection.

We recommend the use of 105°C cables. Ensure that the minimum cable cross-section is at least AWG26/0.13 mm².

Note the following when routing the connection lines:
 For permanently installed lines, the bending radius must be at least four times the outside diameter of the cable.
 For movable lines, the bending radius must be at least 15 times the outside diameter of the cable.

Protective earth contact resistance as per EN 61800-5-1

Compliance with the resistance specifications as per EN 61800-5-1 for the protective earth connection circuit must be verified in the application. Depending on the installation situation, it may be necessary to connect an additional protective earth conductor by way of the extra protective earth terminal provided on the device. The protective earth terminal is located on the housing and provided with a protective earth symbol and a hole.

4.2.2 Power supply connection, fuse protection

Assignment of conductor cross-sections and the fuse protection required for them (overload protection only, no device protection).

Nominal voltage	Safety fuse		Automatic circuit breaker	Wire cross- section	Wire cross- section
	VDE	UL	VDE	mm²	*AWG
3/PE AC 380 - 480 VAC	16 A	15 A	C16A	1.5	16
3/PE AC 380 - 480 VAC	20 A	20 A	C20A	2.5	14
3/PE AC 380 - 480 VAC	25 A	25 A	C25A	4.0	12
3/PE AC 380 - 480 VAC	32 A	30 A	C32A	6.0	10

* AWG = American Wire Gauge

4.2.3 Idle current



Because of the EMC filter integrated for compliance with EMC limits (interference emission and interference immunity), idle currents in the mains cable can be measured even when the motor is at a standstill and the mains voltage is switched on.

- The values are typically in the range < 250 mA
- At the same time, the effective power in this operating state (operational readiness) is typically < 5 W.

4.2.4 Residual current operated device



Only universal (type B or B+) RCD protective devices are permitted. Like frequency inverters, RCD protective devices cannot provide personal safety while operating the device. When switching on the power supply of the device, pulsed charge currents from the capacitors in the integrated EMC filter can lead to the RCD protective devices triggering without delay. We recommend residual current devices with a trigger threshold of 300 mA and delayed triggering (super-resistant, characteristic K).

4.2.5 Leakage current



For asymmetrical power systems or if a phase fails, the leakage current can increase to a multiple of the nominal value.

4.2.6 Locked-rotor protection



Due to the locked-rotor protection, the start-up current (LRA) is equal to or less than the nominal current (FLA).



4.3 Connection in terminal box

4.3.1 Preparing connection lines for the connection



Fig. 1: Recommended stripping lengths in mm (inside terminal box)

Strip the cable just enough so that the screwed cable gland is tight and the terminals are relieved of strain. Tightening torque, see chapter 3.1 Product drawing.



NOTE

Tightness and strain relief depend on the cable used. \rightarrow The user must check this.

4.3.2 Connecting cables with terminals

WARNING

Terminals and connections have voltage even with a unit that is shut off Electric shock

Electric shock

- \rightarrow Wait five minutes after disconnecting the voltage at all poles before opening the device.
- ⇒ Remove the cap from the screwed cable gland.

Remove the cap only in those places where cables are inserted.

- ⇒ Insert the line(s) (not included in the standard scope of delivery) into the terminal box.
- ⇒ First connect the "PE" (protective earth) connection.
- ⇒ Connect the lines to the corresponding terminals.

Use a screwdriver to do so.

During the connection work, ensure that no cables splice off.

⇒ Seal the terminal box.

4.3.3 Cable routing

No water may penetrate along the cable in the direction of the cable gland.



Fig. 2: Fan installed lying flat, cable routed in a U-shaped loop.

When routing the cable, ensure that the screwed cable glands are arranged at the bottom. The cables must always be routed downwards.



Fig. 3: Cable routing for fans installed upright.

4.4 Factory settings

Factory settings with which the device is pre-set by ebm-papst.

Control mode parameter set 1	PWM controlling
Control mode	PWM controlling
parameter set 2	
Fan / device adress	01
Max. PWM / %	100
Min. PWM / %	5
Save set value to	Yes
EEPROM	
Set value control	Analogue (linear)
Control function	Positive (heating)
parameter set 1	
Control function	Positive (heating)
parameter set 2	



4.5 Connection screen



No.	Conn.	Designation	Function / assignment		
	1	PE	Protective earth		
	2	PE	Protective earth		
	3	L1	Power supply		
	4	L2	Power supply		
	5	L3	Power supply		
	6	NC	Status relay, floating status contact, break for failure, contact rating 250 VAC / 2 A (AC1) / min. 10 mA; reinforced insulation on mains side and basic insulation on control interface side		
	7	СОМ	Status relay, floating status contact, break for failure, contact rating 250 VAC / 2 A (AC1) / min. 10 mA; reinforced insulation on mains side and basic insulation on control interface side		
	8	GND	Signal ground for control interface, SELV		
	9	RSA	RS-485 interface for MODBUS, RSA; SELV		
	10	RSB	RS-485 interface for MODBUS, RSB; SELV		
	11	0-10 V	Analogue input (set value) SELV, 0-10 V, Ri=100kΩ, parametrisable curve		
	12	+10 V	Fixed voltage output 10 VDC, SELV, +10 V +/-3%, max. 10 mA short-circuit-proof, power supply for ext. devices (e.g. potentiometer); Fixed voltage input 24 VDC for parameter setting via MODBUS without mains power supply		



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4.6 Checking the connections

- \Rightarrow Make sure that the power is off (all phases).
- ⇒ Secure it from being switched on again.
- ⇒ Check the correct fit of the connection lines.
- ⇒ Screw the terminal box cover closed again. Terminal box tightening torque, see chapter 3.1 Product drawing.
- ⇒ Route the connecting cables in the terminal box so that the terminal box cover closes without resistance.
- ⇒ Use all plug screws (the entire number). In doing so, insert the screws manually to avoid damage to the thread.
- ⇒ Make sure that the terminal box is correctly closed and sealed and that all screws and screwed cable glands are properly tightened.

4.7 Switch on device

The device is not to be switched on until it has been installed properly and in accordance with its intended use, including the required protective devices and professional electrical connection. This also applies to devices which have already been equipped with plugs and terminals or similar connectors by the customer.



Hot motor housing Fire hazard

WARNING

- → Ensure that no combustible or flammable materials are located close to the fan.
- ⇒ Inspect the device for visible external damage and the proper function of the protective features before switching it on.
- ⇒ Check the air flow paths of the fan for foreign objects and remove any that are found.
- ⇒ Apply the nominal voltage to the voltage supply.
- Start the device by changing the input signal.



NOTE

Damage to device by vibrations Bearing damage, reduced service life

→ The fan must operate free of vibrations throughout its speed control range. #Strong vibrations can result from improper handling, imbalance resulting from damage during transport, or component-induced or structural resonances. #When putting the fan into service, determine the speed ranges with excessive vibration levels and also any resonance frequencies that may be present. #When regulating the speed, pass through resonance ranges as quickly as possible or find another remedy.# Operation at excessive vibration levels can lead to premature failure.

4.8 Switching off the device

Switching off the device during operation:

- ⇒ Switch off the device via the control input.
- ⇒ Do not switch the motor (e.g. in cyclic operation) on and off via power supply.

Switching off the device for maintenance work:

- ⇒ Switch off the device via the control input.
- ⇒ Do not switch the motor (e.g. in cyclic operation) on and off via power supply.
- ⇒ Disconnect the device from the supply voltage.

⇒ When disconnecting, be sure to disconnect the earth wire connection last.

5. INTEGRATED PROTECTIVE FUNCTIONS

The integrated protective functions cause the motor to switch off automatically in case of faults described in the table.

Malfunctions	Description / Function of	
	safety feature	
Rotor position detection error	An automatic restart occurs.	
Locked rotor	⇒ After the blockage is	
	removed, the motor restarts	
	automatically.	
Line under-voltage (mains input	⇒ If the mains supply voltage	
voltage outside of permitted	returns to permitted values, the	
nominal voltage)	motor restarts automatically.	
Phase failure	A phase of the supply voltage	
	fails for at least 5 s.	
	⇒ If all phases are correctly	
	supplied again, the motor	
	automatically restarts after 10 -	
	40 s.	

6. MAINTENANCE, MALFUNCTIONS, POSSIBLE CAUSES AND REMEDIES

Do not perform any repairs on your device. Return the device to ebmpapst for repair or replacement.

WARNING

Terminals and connections have voltage even with a unit that is shut off

Electric shock

 \rightarrow Wait five minutes after disconnecting the voltage at all poles before opening the device.

CAUTION

If control voltage is applied or a speed setpoint is stored, the motor will restart automatically, e.g. after power failure.

Risk of injury

- → Keep out of the device danger zone.# When working on the device, switch off the mains power and ensure that it cannot be switched back on.
- → After working on the device, remove any tools used or other objects from the device.



If the device remains out of use for some time, e.g. when in storage, we recommend switching the device on for at least two hours to allow any condensate to evaporate and to move the bearings.

Malfunction/error Possible cause

Possible remedy



K3G310-PT08-J4

Operating instructions

Impeller running	Imbalance in rotating	Clean the device; if	
roughly	parts	imbalance is still	
		evident after cleaning.	
		replace the device.	
		If you have	
		attached any weight	
		clips during cleaning.	
		make sure to remove	
		them afterwards.	
Motor does not turn	Mechanical blockage	Switch off. de-	
		energise, and	
		remove mechanical	
		blockage.	
	Mains supply voltage	Check mains supply	
	faulty	voltage.	
		restore power	
		supply.	
		Important! The error	
		message resets	
		automatically.	
		The device starts up	
		again automatically	
		without advance	
		warning	
	Faulty connection	De-energise, correct	
		connection see	
		connection diagram	
	Motor winding broken	Replace device	
	Thermal overload	Allow motor to cool	
	protector responded	off locate and rectify	
		cause of error if	
		necessary cancel	
		restart lock-out	
	Insufficient cooling	Improve cooling Let	
		the device cool down	
		To reset the error	
		message switch off	
		the mains supply	
		voltage for a min_of	
		25 s and switch it on	
		again.	
		Alternatively reset	
		the error message by	
		applying a control	
		signal of <0.5 V to	
		DIN1 or by short	
		circuiting Din1 to	
		GND	

Ambient temperature too high	Reduce the ambient temperature. Let the device cool down. To reset the error message, switch off the mains supply voltage for a min. of 25 s and switch it on again. Alternatively, reset the error message by applying a control signal of <0.5 V to DIN1 or by short circuiting Din1 to GND.
Unacceptable operating point (e.g. counterpressure is too high)	Correct the operating point. Let the device cool down. To reset the error message, switch off the mains supply voltage for a min. of 25 s and switch it on again. Alternatively, reset the error message by applying a control signal of <0.5 V to DIN1 or by short circuiting Din1 to GND.



If you have any other problems, contact ebm-papst.

6.1 Vibration test

Checking the fan for mechanical vibrations based on ISO 14694. Recommendation: every 6 months. Maximum vibration severity is 3.5 mm/s measured at the motor's fastening diameter on the motor support plate towards and perpendicular to the motor's axis of rotation.



Fig. 4: Example showing vibration measurement. Positioning of the sensors will vary depending on the device and the circumstances of installation.



6.2 Cleaning

NOTE

Damage to the device during cleaning Malfunction possible

- → Do not use a high-pressure cleaner to clean the device.# Do not use any acid, alkali or solvent-based cleaning agents.
- \rightarrow Do not use any pointed or sharp-edged objects for cleaning

6.3 Safety test

NOTE

High-voltage test

The integrated EMC filter contains Y capacitors. Therefore, the trigger current is exceeded when AC testing voltage is applied.

→ Test the device with DC voltage when you carry out the high-voltage test required by law. The voltage to be used corresponds to the peak value of the AC voltage required by the standard.

What has to	How to test?	Frequency	Which
be tested?			measure?
Check the protective casing against accidental contact for damage and to ensure that it is intact	Visual inspection	At least every 6 months	Repair or replacement of the device
Check the device for damage to blades and housing	Visual inspection	At least every 6 months	Replacement of the device
Mounting the connection lines	Visual inspection	At least every 6 months	Fasten
Check the insulation of the wires for damage	Visual inspection	At least every 6 months	Replace wires
Impeller for wear/deposits/ corrosion and damage	Visual inspection	At least every 6 months	Clean or replace impeller
Tightness of screwed cable gland	Visual inspection	At least every 6 months	Retighten, replace if damaged
Condensate discharge holes for clogging, as necessary	Visual inspection	At least every 6 months	Open bore holes
Abnormal bearing noise	acoustic	At least every 6 months	Replace device
Vibration test	Vibration meter, ramp-up or ramp-down measurement	Recommended every 6 months	Clean and rebalance impeller, replace if necessary

6.4 Disposal

For ebm-papst, environmental protection and resource preservation are top priority corporate goals.

ebm-papst operates an environmental management system which is certified in accordance with ISO 14001 and rigorously implemented around the world on the basis of German standards.

Right from the development stage, ecological design, technical safety and health protection are fixed criteria.

The following section contains recommendations for ecological disposal of the product and its components.

6.4.1 Country-specific legal requirements



Country-specific legal requirements

Always observe the applicable country-specific legal regulations with regard to the disposal of products or waste occurring in the various phases of the life cycle. The corresponding disposal standards are also to be heeded.

6.4.2 Disassembly

Disassembly of the product must be performed or supervised by qualified personnel with the appropriate technical knowledge. The product is to be disassembled into suitable components for disposal employing standard procedures for motors.



WARNING

Heavy parts of the product may drop off. Some of the product components are heavy. These components could drop off during disassembly.

This can result in fatal or serious injury and material damage.

 \rightarrow Secure components before unfastening to stop them falling.

6.4.3 Component disposal

The products are mostly made of steel, copper, aluminium and plastic. Metallic materials are generally considered to be fully recyclable. Separate the components for recycling into the following categories:

- Steel and iron
- Aluminium
- Non-ferrous metal, e.g. motor windings
- Plastics, particularly with brominated flame retardants, in accordance with marking
- Insulating materials
- Cables and wires
- Electronic scrap, e.g. circuit boards

Only ferrite magnets and not rare earth magnets are used in external rotor motors from ebm-papst Mulfingen GmbH & Co. KG.

⇒ Ferrite magnets can be disposed of in the same way as normal iron and steel.

Electrical insulating materials on the product, in cables and wires are made of similar materials and are therefore to be treated in the same manner.

The materials concerned are as follows:

- Miscellaneous insulators used in the terminal box
- Power lines
- Cables for internal wiring
- Electrolytic capacitors

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Dispose of electronic components employing the proper procedures for electronic scrap.



 \rightarrow Please contact ebm-papst for any other questions on disposal.



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